

PHYSICS
 REVIEW: WORK; ENERGY; SIMPLE MACHINES

TEST DATE = _____

work	simple machines
power	effort force
kinetic energy	effort distance
potential energy (gravitational)	resistance force
potential energy (spring)	resistance distance
Hooke's Law	work input
spring constant	work output
conservation of energy	efficiency
elastic and inelastic collisions	ideal mechanical advantage
rotational and translational KE	actual mechanical advantage

work = F x d

kinetic energy = 1/2 mv²

potential energy (gravitational) = mgh

potential energy (spring) = 1/2 kx²

heat (from friction, etc.)

all the forms of energy listed above have units kg m² /sec² = Nm = joule

power = rate of doing work = $\frac{\text{work}}{\text{time}} = \frac{W}{t}$ unit of power = watt

in the systems we have dealt with, energy can be redistributed among the above forms, but not "created" or "destroyed"...energy is CONSERVED...there are forms of energy we have not considered in our work, that could be added to the list above, e.g. rotational kinetic energy (considered briefly, but not quantitatively), chemical energy, electrical energy, light energy, etc....

a collision in which both momentum and kinetic energy are conserved is said to be elastic...momentum will always be conserved in an isolated system, but kinetic energy may not (though total energy is)...

Win = F_ed_e Wout = F_rd_r %Efficiency = $\frac{\text{Work (out)}}{\text{Work (in)}} \times 100$

AMA = $\frac{F_r}{F_e}$ IMA = $\frac{d_e}{d_r}$ % Efficiency = $\frac{\text{AMA}}{\text{IMA}} \times 100$

output is never greater than input...efficiency is never more than 100%

simple machines do not give a "work advantage"...they most commonly give a "force advantage" at the expense of distance...you always put more work into a simple machine than you get out

rotational kinetic energy = 1/2 I ω²

KE_{total} = KE_{translational} + KE_{rotational}